

One More Class of Sequential Circuits having Combinational Test Generation Complexity

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Abstract The paper uses the concept of time expansion model to find the test generation for acyclic sequential circuits. Any acyclic sequential circuit without hold registers can be tested with combinational test generation complexity using this model. We show that for acyclic sequential circuits having hold registers, a subset of such circuits can also be tested with this complexity. We define the max-testable class of sequential circuits that includes both these groups. The paper also suggests an algorithm to find such class of circuits.

Keywords Acyclic sequential circuits · Hold registers · Combinational test generation · Time expansion model

1 Introduction

Generally, it is believed that the cyclic structures of sequential circuits are mainly responsible for making the test generation of sequential circuits more complex. But even acyclic sequential circuits do not allow test generation with combinational test generation complexity. Several attempts [1, 3–5, 7–9] were reported earlier to find the classes of acyclic sequential circuits that can provide combinational test generation complexity. If the acyclic sequential circuit contains hold registers, the situation becomes worse. Hold registers are sometimes used in sequential circuits to hold values for later use to

implement the desired functioning and they are using the same clock. In [7], the problem of hold registers was solved by scanning these registers.

In this paper we explore the properties of TEG [2, 6, 7], which lead us to identify a class of acyclic sequential circuits called as max-testable class for which test generation can be obtained by running a combinational test generator with capability of detecting multiple faults on a combinational kernel. This class includes (i) all acyclic sequential circuits without hold registers including strongly balanced [1], balanced [5], internally balanced [9] circuits and (ii) a subset of sequential circuits containing hold registers. We also present an algorithm to search for such class of circuits.

2 Preliminaries

2.1 Time Expansion Graph (TEG)

Definition 1 [2] A *topology graph* (TG) is a directed graph $G = (V, A, r)$, where a vertex $v \in V$ denotes a logic block and an arc $(u, v) \in A$ denotes a connection from u to v and each arc has a label $r: A \rightarrow Z^+ \cup \{h\}$ (non-negative integers) $\cup \{h\}$. When two logic blocks u and v are connected through one or more L-registers, the label $r(u, v)$ denotes the number of L-registers (i.e., $r(u, v) \rightarrow Z^+$). When two logic blocks u, v are connected through one hold register, the label $r(u, v) = h$.

Example 1 Consider a sequential circuit S shown in Fig. 1a, in which 1, 2, 3 and 4 are logic blocks, b, c, d , and e are L-registers, and a which is highlighted, is a Hold register. The topology graph G_1 of S is shown in Fig. 1b.

Definition 2 A vertex in a directed graph is called as a *sink vertex*, if there is no outgoing edge from the vertex.

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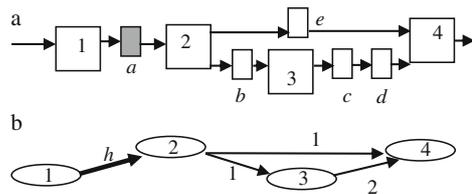


Fig. 1 a The sequential circuit S b: The topology graph G1 of S

Definition 3 The set of direct predecessors [successors] of any vertex u in a directed graph is denoted as $pre(u)$ [$suc(u)$].

Definition 4 (Time-expansion graph (TEG)): Let S be an acyclic sequential circuit and let $G = (V, A, r)$ be the topology graph of S . Let $E = (V_E, A_E, t, l)$ be a directed graph, where V_E is a set of vertices, A_E is a set of arcs, t is a mapping from V_E to a set of integers, and l is a mapping from V_E to the set of vertices in G . If graph E satisfies the following five conditions, graph E is said to be a time-expansion graph (TEG) of G .

C1(Logic Preservation): The mapping l is a surjective, i.e., $\forall v \in V, \exists u \in V_E$ such that $v=l(u)$

C2(Input preservation): Let u be a vertex in E . For any direct predecessor $v (\in pre(l(u)))$ of $l(u)$ in G , there exists a vertex u' in E such that $l(u') = v$ and $u' \in pre(u)$.

C3(Time consistency): For any arc $(u, v) (\in A_E)$, there exists a corresponding arc $(l(u), l(v))$, and if $r(l(u), l(v)) \in \mathbb{Z}^+$, then $r(l(u), l(v)) = t(v)-t(u)$, or else $(r(l(u), l(v)) = h, t(u) < t(v)$.

C4(time uniqueness): For any pair of vertices $u, v (\in V_E)$, if $t(u) = t(v)$ and $l(u) = l(v)$, then the vertices u and v are identical, i.e., $u = v$.

C5(Hold consistency): For any pair of arcs $(u_1, v_1), (u_2, v_2) (\in A_E)$ such that $(l(u_1), l(v_1)) = (l(u_2), l(v_2))$ and $r(l(u_1), l(v_1)) = r(l(u_2), l(v_2)) = h$, if $t(v_1) > t(v_2)$, then either $t(u_1) = t(u_2)$ or $t(u_1) \geq t(v_2)$.

Example 2 Figure 2a is a TEGs E_1 of the TG G (Fig. 1b). The mappings t and l are shown in Fig. 2b and c respectively.

Definition 5 A path from a vertex u_1 to u_k in a TG $G(V, A, r)$ [TEG $E(V_E, A_E, t, l)$] is obtained by concatenation of several arcs $(u_1, u_2), (u_2, u_3), (u_3, u_4), (u_4, u_5), \dots, (u_{k-1}, u_k)$ $i, 1 < i < (k-1)$, where $(u_i, u_{i+1}) \in A [A_E]$.

Definition 6 The length of an arc $(v_1, v_2) \in A_E$ in a TEG $E(V_E, A_E, t, l)$, denoted as $len(v_1, v_2)$ is given by $t(v_2) - t(v_1)$.

Definition 7 The length of a path in a TEG is the summation of the lengths of the different arcs in it.

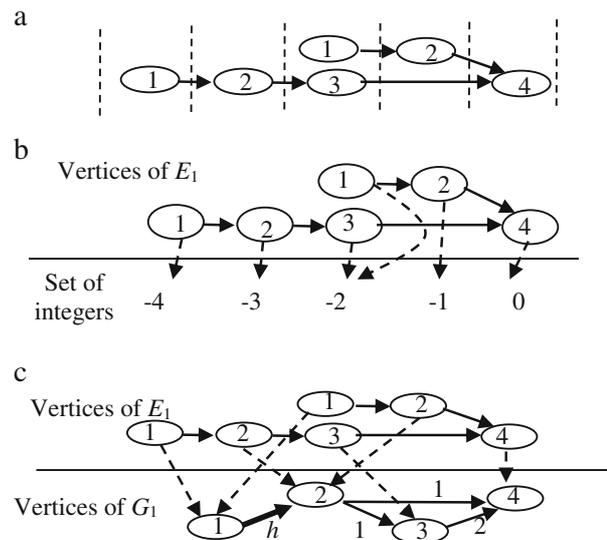


Fig. 2 a TEG of G1: E1 b: Mapping t from the vertices of TEG E_1 of Fig. 2a to a set of integers c: Mapping l from the vertices of TEG E_1 of a to the vertices of TEG G of Fig. 1b

Definition 8 Given a TG $G(V, A, r)$ let $E(V_E, A_E, t, l)$ be any TEG of it, let p be a path from a vertex u_1 to u_k in E obtained by concatenation of the arcs $(u_1, u_2), (u_2, u_3), (u_3, u_4), (u_4, u_5), \dots, (u_{k-1}, u_k)$ $i, 1 < i < (k-1)$, where $(u_i, u_{i+1}) \in A [A_E]$. The path p' in TG from the vertex v_1 to v_k in TG G passing through vertices $(v_1, v_2, v_3, \dots, v_k)$, where each $v_i = l(u_i)$ is called as the corresponding path of p .

2.2 Time Expansion Model (TEM)

Definition 9 [6] Let S be an acyclic sequential circuit, let $G = (V, A, r)$ be the topology graph of S , and let $E = (V_E, A_E, t, l)$ be a TEG of G . The combinational circuit $C_E(S)$ obtained by the following procedure is said to be the *time expansion model (TEM)* of S based on E .

- (1) For each vertex $u \in V_E$, let logic block $l(u) (\in V)$ be the logic block corresponding to u .
- (2) For each arc $(u, v) \in A_E$, connect the output of u to the input of v with a bus in the same way as $(l(u), l(v)) (\in A)$. Note that the connection corresponding to (u, v) has no register even if the connection corresponding to $(l(u), l(v))$ has a register (i.e., $r(l(u), l(v)) \neq 0$).
- (3) In each logic block, lines and logics that are reachable to neither other logic blocks nor primary outputs are removed.

Example 3 Figure 3 is a TEM of the sequential circuit S (Fig. 1a) based on TEG E_1 (Fig. 2a). The integer mapping t of E_1 is also shown.

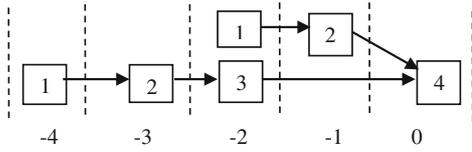


Fig. 3 TEM of S based on E1 of Figs. 2a and b

Theorem 1 [6] Let S be an acyclic sequential circuit, and let F be the set of faults in S . Let $G = (V, A, r)$ be the TG of S .

- 1) A fault $f \in F$ is testable (or irredundant) in S if and only if there exists a TEG E of G such that the fault $f_e \in F_e$, corresponding to f is testable in the TEM $C_E(S)$ based on E .
- 2) A test pattern for a fault $f_e (\in F_e)$ obtained using a TEM $C_E(S)$ can be transformed into a test sequence for the fault $f (\in F)$ corresponding to fault f_e .

From this theorem, we can see that test generation for an acyclic sequential circuit can be performed by using several different TEMs. Furthermore, since TEMs are fully combinational, a combinational test generator can be used for the test generation provided the test generator can deal with the multiple faults. Given an acyclic sequential circuit S , if we can derive all TEMs obtained from it and find the tests for these TEMs using combinational test generator for multiple faults, then it is sufficient to obtain the set of test sequences to detect the faults in S . However, this test generator has not to generate the tests for all possible multiple faults in each TEM as it has to find out tests for only those multiple faults which are occurring in several identical blocks of the TEM.

3 Cover Relation

Definition 10 Let u is a vertex in TG G and let $E(V_E, A_E, t, l)$ be any TEG of G . The cone subgraph E' (E, u) of E with respect to u is defined as the maximal sub-graph of E in which $u_E [l(u_E) = u]$ is the only sink vertex, i.e., there is no other vertex v_E in E' , for which $l(v_E) = u$.

Definition 11 [2] Let $G = (V, A, r)$ be the TG of an acyclic sequential circuit S , and let $E_1(V_1, A_1, t_1, l_1)$ and $E_2(V_2, A_2, t_2, l_2)$ be arbitrary TEGs of G . Let s be any sink vertex in G . Let $E'_1(E_1, s) = (V'_1, A'_1)$ [$E'_2(E_2, s) = (V'_2, A'_2)$] be the cone subgraph of E_1 [E_2] with respect to s , where V'_1 and A'_1 [V'_2 and A'_2] are respectively the set of vertices and arcs in E'_1 [E'_2]. TEG E_1 is said to cover TEG E_2 if there exists a mapping m from V'_1 to V'_2 , such that for every s , (i) $m(s_1) = s_2$, where $l_1(s_1) = l_2(s_2) = s$ (ii) if $v_2 = m(v_1)$, for $v_1 \in V'_1$ and $v_2 \in V'_2$, then for any pair of vertices $u_1 \in pre(v_1)$ and $u_2 \in pre(v_2)$ if $l_1(u_1) = l_2(u_2)$, then $u_2 = m(u_1)$.

Example 4 Consider the TG G_2 of Fig. 4a. Its two TEGs E_2 and E_3 are shown in Fig. 4b and c respectively. E_2 covers E_3 with the mapping shown in Fig. 4d and e.

Definition 12 Given a TG, if there exist two TEGs E_1 and E_2 for it such that E_1 covers E_2 and E_2 covers E_1 , then E_1 and E_2 are said to be equivalent.

Lemma 1 If E_1 and E_2 be two TEGs of a TG G where E_1 covers E_2 , then the test set generated for the TEM of E_1 is sufficient to detect any fault in TEM of E_2 .

The above Lemma establishes the importance of finding the cover relations between the different TEGs of a given TG. Because, if we can find the set of minimum number of TEGs, that cover all possible TEGs of TG, then the test set generated from the TEMs corresponding to this set of TEGs is sufficient to detect the faults of all possible TEMs. From

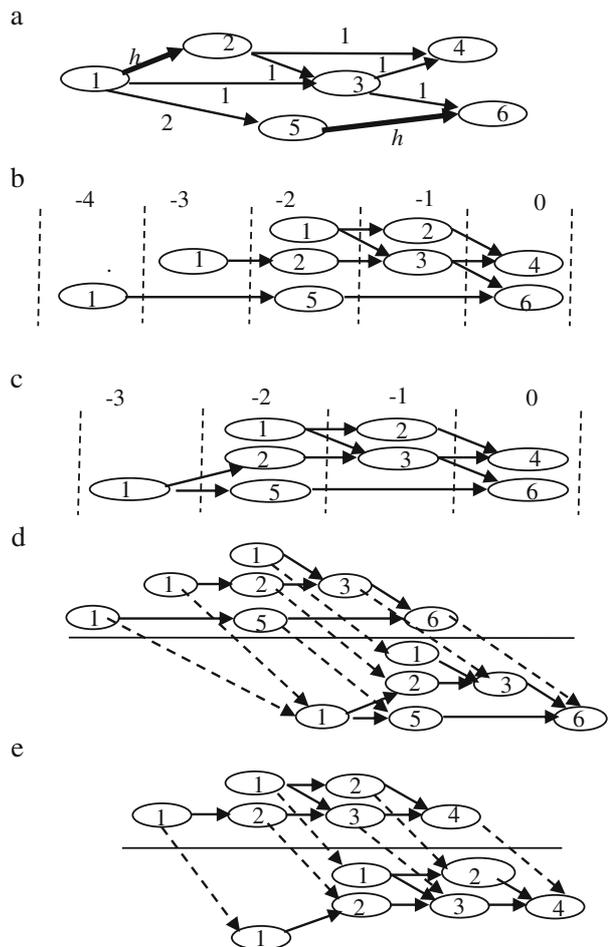


Fig. 4 a TG G_2 b: TEG E_2 of G_2 c: TEG E_3 of G_2 d: The mapping m with respect to sink node 6 e: The mapping m with respect to sink node 4

Theorem 1, this test set can be transformed to a set of test sequence to detect all faults in the sequential circuit.

Given two TEGs E_1 and E_2 for a TG G , to determine that whether E_1 covers E_2 , we have to find the mapping m , if exists as defined in Definition 11. The algorithm to find this cover relation is given in [2].

3.1 Maximum TEG

Definition 13 [2] Given a TG G , a TEG E which cannot be covered by any other TEG of G except by its equivalent TEG, is called a *maximal TEG* of G . If number of maximal TEGs is one, then that maximal TEG is called as the *maximum*.

Definition 14 If a sequential circuit has a maximum TEG, then that circuit is *max-testable*.

If a sequential circuit S is max-testable, then by finding the test set of the TEM of its maximum TEG, we can generate the test sequence to detect all faults in S (Lemma 1 and Theorem 1). If a sequential circuit has a maximum TEG, how can we find out that? One method may be to draw all TEGs, and then find the maximum TEG among them that covers any other TEG and cannot be covered by anyone else. Obviously, this process is time consuming and impractical. The best way to achieve this is to draw it in such a manner such that it follows the properties of the maximum TEGs. The question is- while we achieve a TEG, is it easy to confirm whether this TEG is maximum or not? In some special cases, the features in a TEG clearly indicate whether it is maximum or not.

Lemma 2 [2] Given a TEG, if it has no re-convergent fanout, then it is maximum TEG.

Lemma 3 [2] Consider a hold arc $h(h_1, h_2)$ in a TG $G(V, A, r)$. Let $E = (V_E, A_E, t, l)$ is a TEG of G . Consider two different vertices v_1 and $v_2 \in V_E$, such that $l(v_1) = l(v_2) = h_2$. If there exists a vertex $u \in V_E$ such that $l(u) = h_1$ and $u \in pre(v_1)$ and $u \in pre(v_2)$, then E cannot be a maximum TEG.

Lemma 4 [2] Let a TEG E has re-convergent fan-outs. If for every such re-convergent fan-out, no path in the re-convergent loop contains an arc that corresponds to a hold arc in TG, then E is maximum.

Definition 15 Two paths p_1 and p_2 in a TG $G(V, A, r)$ [TEG $E(V_E, A_E, t, l)$] are parallel to each other with respect to an arc $(v_1, v_2) \in A [A_E]$ if both head and tail vertices of the two paths are same and the arc (v_1, v_2) is not common to both p_1 and p_2 .

Theorem 2 Consider a TEG $E(V_E, A_E, t, l)$ of a TG $G(V, A, r)$. The necessary condition for E not to be maximum TEG, is that if there exists a pair of vertices $u, v \in V_E$, such that there are at

least two parallel paths p_1 and p_2 between u and v , with respect to an arc (v_1, v_2) , such that $r(l(v_1), l(v_2)) = h$.

After obtaining a TEG from a TG, we can easily confirm whether that TEG is maximum or not. If it is found to be maximum, we need not draw the other TEGs to compare them with it. But suppose we fail, i.e., given a TG we get a TEG E but find that it is not maximum. We then try to obtain another TEG. For a simple structured TG, it may not be a hard task to try for all other alternatives. But, for a complex structure with several hold registers and paths this may not be so easy. Moreover, a TG may not have any maximum TEG. Thus, our efforts may be futile after searching of the different possibilities. The question is, by observing the TG can we confirm that whether this TG has a maximum TEG or not and if it has maximum TEG, how to obtain that in one chance.

4 The Properties of a Circuit to Have Maximum TEG

If any arc $(v_1, v_2) \in A_E$ in a TEG $E(V_E, A_E, t, l)$ of a TG $G(V, A, r)$ is a non-hold arc, $len(v_1, v_2)$ is always fixed and given by $r(u_1, u_2)$, where $u_1 = l(v_1)$ and $u_2 = l(v_2)$. But if (v_1, v_2) corresponds to a hold arc what can be the value for $len(v_1, v_2)$? As a hold register can hold a value for arbitrary amount of time, this $len(v_1, v_2)$ can be any value between 1 and infinity. But there are some restrictions as this length depends on the length of other paths, as evident from the following Lemma.

Lemma 5 Consider a TEG $E(V_E, A_E, t, l)$ of TG $G(V, A, r)$. Let there be two arcs (v_1, v_2) and $(v'_1, v'_2) \in A_E$ in the TEG, such that $r(l(v_1), l(v_2)) = r(l(v'_1), l(v'_2)) = h$, where h is a hold arc in G . For $t(v_2) < t(v'_2)$, with $d = t(v'_2) - t(v_2)$,

- (i) If $len(v'_1, v'_2)$ is chosen as any value k such that $k > d$, then $len(v_1, v_2) = k - d$,
- (ii) If $len(v_1, v_2)$ is chosen as any value $k > 0$, then $len(v'_1, v'_2)$ is either (a) between 1 and d or (b) $k + d$.

Given a TG, to have its maximal or maximum (if it exists) TEG, we have to draw the TEG in such a manner such that no hold-start vertex can lie in the predecessor of two hold-end vertices. If the TEG is maximal or maximum then the length of hold-arc cannot be always any arbitrary value.

Definition 16 Let u and v are two vertices in a TG, and there is a path p between them which does not contain any hold arc, then there exists a *fixed length* between u and v along the path p , which is given by the summation of the lengths of the different arcs along the path.

Definition 17 Consider a TG $G(V, A, r)$ where $(h_1, h_2) \in A$ is a hold arc and $u \in V$ is a vertex reachable from h_2 . Let there be at least two paths from h_2 to u . Let in each TEG $E(V_E, A_E, t, l)$ of G ,

v_1, v_2 and $w \in V_E$, are three vertices such that (i) $l(v_1)=l(v_2)=h_2$ (ii) $l(w)=u$ and (iii) $t(v_1)<t(v_2)$. Let $p_1^* [p_2^*]$ is the path from $v_1 [v_2]$ to w in E and $p_1 [p_2]$ is the corresponding path in G . Let the path $p_3 [p_4]$ in TG is obtained by concatenation of hold arc (h_1, h_2) with $p_1 [p_2]$, then p_3 is unbounded with respect to the path p_4 .

Example 5 Consider the TG of Fig. 4a. The arc (1,2) is a hold arc. There are two paths from 2 to 4. In each TEG $E(V_E, A_E, t, l)$ we may get three vertices v_1, v_2 and $w \in V_E$, such that (i) $l(v_1)=l(v_2)=2$ (ii) $l(w)=4$ and (iii) $t(v_1)<t(v_2)$. Thus in the TG, the path 1-2-3-4 is unbounded with respect to path 1-2-4.

Definition 18 In a TG, if an unbounded path exists with respect to a path p , then the path p is a bounded path in TG.

Lemma 6 Consider a TG $G(V, A, r)$ where $(h_1, h_2) \in A$ is a hold arc and $w \in V$ is a vertex reachable from h_2 . Let there be at least two non-hold paths from h_2 to w having two different lengths. Then there exist

- (i) one TEGs $E1(V_{E1}, A_{E1}, t1, l1)$ having three different vertices u_1, u_2 and u_3 in $E1$ with $l1(u_1)=h_1, l1(u_2)=l1(u_3)=h_2$, and $pre(u_1)=pre(u_2)=u_1$,
- (ii) one TEGs $E2(V_{E2}, A_{E2}, t2, l2)$ having four different vertices v_1, v'_1, v_2, v_3 in $E2$ with $l2(v_1)=l2(v'_1)=h_1, l2(v_2)=l2(v_3)=h_2$, and $pre(v_1) \neq pre(v_2)$.

Definition 19 Suppose in a TG, p_1 is unbounded path with respect to bounded path p_2 . Then p_2 has a bounded range given by a pair of positive integers (n_1, n_2) where $n_1 \leq n_2$. The values of n_1 and n_2 are obtained in such a manner such that in any TEG $E(V_E, A_E, t, l)$ of TG G , for the pair of paths p_1^* and p_2^* in E with p_1 and p_2 respectively be the corresponding paths in G , if the length of the path p_2^* in E is any value between n_1 and n_2 (both inclusive) with the condition that p_1^* and p_2^* has no common vertex v for which $l(v)=h_1$.

Example 6 Consider the TG of Fig. 4a. The arc (1,2) is a hold arc. The path 1-2-3-4 is unbounded with respect to path 1-2-4. The path 1-2-4 is bounded by a range $\{2, 2\}$.

Example 7 The topology graph G_3 is shown in Fig. 5. The arc (1,2) is a hold arc. The path 1-2-3-4 is unbounded with respect to path 1-2-4. The path 1-2-4 is bounded by a range $\{2, 4\}$.

Lemma 7 Consider a hold arc (v_1, v_2) in a TG $G(V, A, r)$, where $r(v_1, v_2)=h$. Let v is a vertex reachable from v_2 by two non-hold paths p_1 and p_2 with fixed lengths d_1 and d_2 respectively where

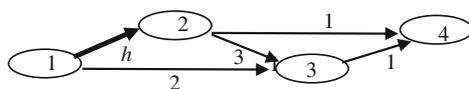


Fig. 5 TG G3

$d_1 < d_2$, (let there is no other path from v_2 to v). Let is $p'_1 [p'_2]$ is the path from v_1 to v that includes $p_1 [p_2]$. Then the following holds

- (i) the path p'_1 is a bounded path in G with a bounded range $\{(d_1+1), d_2\}$
- (ii) the path p'_2 is unbounded with respect to p'_1 .

Definition 20 If between two vertices u and v in a TG, there exists a bounded path p , bounded by a range $\{l, l'\}$, then there exists a bounded length l_{bound} of p which equals to any integer value in the bounded range $\{l, l'\}$ i.e., $l \leq l_{bound} \leq l'$.

Example 8 The l_{bound} of bounded path 1-2-4 of Fig. 5 is any value in the range $\{2, 4\}$, i.e., $2 \leq l_{bound} \leq 4$.

If there are several bounded paths between u and v , there exist several bounded lengths between u and v , whose values depend on how we assign them in appropriate bounded ranges.

Theorem 3 A TG G , has no maximum TEG iff u being the hold-start vertex, and between two vertices u and v in G , there exists one or more bounded paths, and whatever be the assignment, the bounded length of a bounded path p becomes always equal to bounded or fixed distance of any other path p' between u and v , where p and p' are parallel to each other with respect to an arc (h_1, h_2) where $r(h_1, h_2)=h$.

Lemma 8 If a TG has no maximum TEG, then there exist two vertices u and v in TG, such that there are two paths between u and v , where one of them is bounded and the other is either bounded or fixed.

Lemma 9 If a TG has no maximum TEG, then there exist two vertices u and v in TG, such that there are at least three paths between u and v .

Example 9 The circuit of Fig. 1a is max-testable as there are only two paths (Lemma 9).

Theorem 4 A TG $G(V, A, r)$ is having a maximum TEG, iff

- (i) it has no bounded path, or
- (ii) if for each bounded path p between two vertices, there exists a bounded length which is not equal to bounded or fixed length of any other path p' between u and v , where

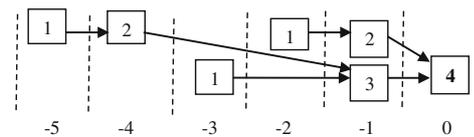


Fig. 6 TEM of the max-testable circuit of Fig. 5 on which combinational test generation algorithm is to be run

p and p' are parallel to each other with respect to an arc (v_1, v_2) where $r(v_1, v_2) = h$.

Example 10 The circuit corresponding to TG of Fig. 4a is not max-testable, because the bounded length of the path 1-2-4 is equal to the fixed length of the path 1-3-4.

Example 11 Consider the TG of Fig. 5. Its path 1-2-4 has the bounded range $\{2, 4\}$. There is another path 1-3-4 parallel to

1-2-4 with respect to hold arc (1,2). This path has a fixed length 3. Thus, we may assign the bounded length of 1-2-4 as 2 or 4 to satisfy the condition (ii) of Theorem 4. Hence the circuit corresponding to TG of Fig. 5 is max-testable. The corresponding TEM is shown in Fig. 6 with integer mapping t of the maximum TEG.

The question is, even if a TG has a maximum TEG, how we can find out that. The following algorithm is given for that.

Algorithm to find maxtestability

for each sink vertex s in a TG $G(V, A, r)$

- (i) Find the set H of hold-start vertices, s.t. for all $u \in H$, there exists at least 3 paths to s and only two of which contain a common hold arc,
 - (ii) for each $u \in H$
 - (a) find all the bounded ranges and fixed distances from u to s
 - (b) assign the bounded distances
 - (c) if bounded distance of a path p becomes equal to bounded or fixed distance of another path p' , where p and p' has at least one uncommon hold arc, then try for another assignment in (b), if no other assignment exists, then report 'not maximum' and return
 - (d) Draw TEG with the assignment, it is maximum.
- Return.
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5 Conclusion

We used time expansion model (TEM) to have the test sequences for acyclic sequential circuits. To obtain the TEMs of a sequential circuit, we used time expansion graphs (TEG). We identify a class of acyclic sequential circuits, called as max-testable class for which the test sequences can be easily achieved by running a combinational test generation tool on a TEM of the circuit, obtained by finding a particular TEG called as maximum TEG. The combinational test generator should have the capability of detecting multiple faults. We presented an algorithm to find max-testable class of circuits. Any acyclic sequential circuit with no hold register belongs to the max-testable class. A subset of the acyclic sequential circuits which have hold registers belong to max-testable class. Given an acyclic sequential circuit, we presented an algorithm to determine whether it belongs to max-testable class or not and if it belongs to max-testable class we also find the TEM on which the test generator tool is to be run.

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